OBJECTIVES:

17BECE601

- To understand the influence line concepts for indeterminate structures
- To understand the methods of analysis of intermediate trusses for external loads, lack of fit and thermal effect
- To study behaviour of arches and their methods of analysis
- To know the concept and analysis of cable stayed bridge
- To study the multi storey frames subjected to gravity loads and lateral loads

UNIT I

Indeterminate structures - Slope deflection method - Continuous beams and fixedbeam-Simplification of hinged end – support settlement - Simple frames - Portal frames Consistent-deformation method-continuous beams

UNIT II

Strain energy method- Castigliano's theorem- Deflection by strain energy method – evaluation of strain energy in member under different loading - Application of strain energy method for Beams and frames - Beams curved in plan.

UNIT III

Flexibility method -Equilibrium and Compatibility - Determinate vs Indeterminate structures -Indeterminacy - Primary Structure - Compatibility conditions - Analysis of indeterminate pin jointed plane frames, continuous beams, rigid jointed plane frames (with redundancy restricted to two).

UNIT IV

Stiffness method-Beams-Trusses-Simple frames-Portal frames-Grids-Lack of fit-Temperature stresses-Support settlements-Elastic supports.(Direct approach)- Introduction to Finite element.

UNIT V

Plastic Analysis of Structures : Statically indeterminate axial problems - Beams in pure bending – Plastic moment of resistance – Plastic modulus – Shape factor – Load factor – Plastic hinge and mechanism – Plastic analysis of indeterminate beams and frames.

Sl.N o	Title of Book	Author of Book	Publisher	Year of Publishing
1	Strength of materials and Theory of Structures Vol.I, II	Dr.B.C.Punmia	Laxmi Publication, New Delhi	2012

TOTAL:60HRSTEXT BOOKS:

12

12

12

12

12

DEFEDENCE DOOLS.					

REFERENCE BOOKS:

Sl.N o	Title of the Book	Author of the Book	Publisher	Year of Publishing
1	Intermediate Structural Analysis	C.K. Wang	McGraw-Hill, New Delhi	2002
2	Matrix Analysis of Framed structures	W.Weaver and J.M Gere	Van NostrandReinhold,Ne w York	2003
3	Structural analysis, a matrix approach	G.S.Pandit and S.P.Gupta	Tata McGraw Hill	2004
4	Theory of structures	S.Ramamrutham&R.Naraya n	DhanpatRai Publishing Co, New Delhi	2013
5	Analysis of Structures- Vol.II	Prof.V.N. Vazirani, Dr.M.M.Ratwani, Dr.S.K.Duggal	Khanna Publishers, Chennai	2012

WEBSITES:

- http://www.icivilengineer.com
- http://www.engineeringcivil.com/
- http://www.aboutcivil.com/
- http://www.engineersdaily.com
- http://www.asce.org/
- http://www.cif.org/
- http://icevirtuallibrary.com/
- http://www.ice.org.uk/
- http://www.engineering-software.com/ce/

COURSE OUTCOMES

On completion of the course, the students will be able to:

- Demonstrate the concepts of qualitative influence line diagram for continuous beams and frames
- Apply the methods of indeterminate truss analysis.
- Demonstrate the behavior of arches and their methods of analysis.
- Analyse cable suspension bridges.
- Analyse multistory frames subjected to gravity loads and lateral loads.

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CE6501 STRUCTURAL ANALYSIS I UNIT IV SLOPE DEFLECTION METHOD

4.1 Continuous beams without sway

4.2 Continuous beams with sway

4.3 Rigid frames without sway

4.4 Rigid frames with sway

4.5 Symmetry and antisymmetry

4.6 Simplification for hinged end

4.7 Support displacements

Assumptions In The Slope- Deflection Method

- > The material of the structure is linearly elastic.
- > The structure is loaded with in elastic limit.
- Axial displacements ,Shear displacements are neglected.
- > Only flexural deformations are considered.
- > All joints are considered rigid.

INTRODUCTION

- The slope deflection method is a structural analysis method for beams & frames introduced in 1914 by George A. Maney.
- This method considers the deflection as the primary unknowns, while the redundant forces were used in the force method. Hence this method is the displacement method.
- In the slope-deflection method, the relationship is established between moments at the ends of the members and the corresponding rotations and displacements.
- An important characteristic of the slope-deflection method is that it does not become increasingly complicated to apply as the number of unknowns in the problem increases. In the slopedeflection method the individual equations are relatively easy to construct regardless of the number of unknowns

SIGN CONVENTION

- Clockwise moment and clockwise rotation are taken as negative ones.
- The down ward displacements of the right end with respect to the left end of horizontal member is considered as positive.
- The right ward displacement of upper end with respect to lower end of a vertical member is taken as positive.



General Procedure OF Slope-Deflection Method

- Find the fixed end moments of each span (both ends left & right).
- Apply the slope deflection equation on each span & identify the unknowns.
- Write down the joint equilibrium equations.
- Solve the equilibrium equations to get the unknown rotation & deflections.
- Determine the end moments and then treat each span as simply supported beam subjected to given load & end moments so we can work out the reactions & draw the bending moment & shear force diagram.



• We find that the second terms on the right sides of Eqs. 6 are equal to the fixed-end moments.

$$M_{AB} = \frac{2EI}{L} \left(2_A + B_B - FEM_{AB} \right)$$
(1)

$$M_{BA} = \frac{2EH}{L} \begin{pmatrix} A + 2B & -3 \end{pmatrix} + BA$$
 (2)

- Equations (1&2), which express the moments at the ends of a member in terms of its end rotations and translations for a specified external loading, are called slope-deflections equations.
- These equations are valid for prismatic members, composed of linearly elastic material and subjected to small deformations.
- The deformations due to axial and shear forces are neglected.

• The two slope-deflection equations have the same form and either end of equations can be obtained from the other simply by switching the subscript A and B.

$$M_{nf} = \underline{2EI} \left(2_{n} + f - nf \right)$$
(9)

in which the subscript n refers to the near end of the member where moment $M_{\mbox{\tiny nf}}$ acts and the subscript f identifies the far (other) end of the member.

4.1 Continuous beams without sway Problem: 1

Analyze two span continuous beam ABC by slope deflection method. Then draw Bending moment & Shear force diagram. Take El constant.





Step: 2 Stope deflection equations are $M_{AB} = M_{FAB} + \frac{2EI}{L} [2\theta_A + \theta_B] = -44.44 + \frac{2EI}{6} \theta_B = -44.44 + \frac{EI}{3} \theta_B \quad \dots \dots (1)$ $M_{BA} = M_{FBA} + \frac{2EI}{L} [2\theta_B + \theta_A] = 88.89 + \frac{4EI}{6} \theta_B = 88.89 + \frac{2EI}{3} \theta_B \quad \dots \dots (2)$ $M_{BC} = M_{FBC} + \frac{2EI}{L} [2\theta_B + \theta_C] = -41.67 + \frac{4EI}{5} \theta_B + \frac{2EI}{5} \theta_C \quad \dots \dots (3)$ $M_{CB} = M_{FCB} + \frac{2EI}{L} [2\theta_C + \theta_B] = 41.67 + \frac{4EI}{5} \theta_C + \frac{2EI}{5} \theta_B \quad \dots \dots (4)$







Find reactions using equations of equilibrium. Span AB: $\Sigma M_A = 0$, $R_B \times 6 = 100 \times 4 + 75 - 51.38$ $\therefore R_B = 70.60 \text{ KN}$ $\Sigma V = 0$, $R_A + R_B = 100 \text{ KN}$ $\therefore R_A = 100 - 70.60 = 29.40 \text{ KN}$ Span BC: $\Sigma M_C = 0$, $R_B \times 5 = 20 \times 5 \times \frac{5}{2} + 75$ $\therefore R_B = 65 \text{ KN}$ $\Sigma V = 0 R_B + R_C = 20 \times 5 = 100 \text{ KN}$ $R_C = 100 - 65 = 35 \text{ KN}$ Using these data BM and SF diagram can be drawn





Degrees of Freedom Identify the unknown independent displacements (translations and rotations) of the joints of the structure. These unknown joint displacements are referred to as the degrees of freedom of the structure. From the qualitative deflected shape of the continuous beam shown in Figure below, we can see that none of its joints can translate. 30 k 1.5 k/ft θ_cC 20 ft θ_B B 10 ft 10 ft 15 ft The fixed joints A and D cannot rotate, whereas joints B and C are free to rotate. ³⁰ 19 MZCET/CIVIL/V-A&B/CE6501/SA I/IV



Equations of Equilibrium

The unknown joint rotations are determined by solving the equations of equilibrium of the joints that are free to rotate. The free body diagrams of the members and joints B and C of the continuous beam are shown.



Equations of Equilibrium

Because the entire structure is in equilibrium, each of its members and joints must also be in equilibrium. By applying the moment equilibrium equations $\Sigma M_B = 0$ and $\Sigma M_C = 0$, respectively, to the free bodies of joints B and C, we obtain the equilibrium equations





Equations of Equilibrium

In addition to the external loads, each member is subjected to an internal moment at each of its ends.

The correct senses of the member end moments are not yet known, it is assumed that the moments at the ends of all the members are positive (counterclockwise).

The free body diagrams of the joints show the member end moments acting in an opposite (clockwise) direction in accordance with Newton's law of action and reaction.



Slope-Deflection Equations

The equilibrium equations Eqs. (17) can be expressed in terms of the unknown joint rotations, θ_{B} and θ_{c} , by using slope-deflection equations that relate member end moments to the unknown joint rotations.

Before we can write the slope-deflection equations, we need to compute the fixed-end moments due to the external loads acting on the members of the continuous beam.

To calculate the fixed-end moments, we apply imaginary clamps at joints B and C to prevent them from rotating.

Or we generally provide fixed-supports at the ends of each member to prevent the joint rotations as shown.

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Slope-Deflection Equations

The slope-deflection equations for the three members of the continuous beam can now be written by using Eq. (9).

Since none of the supports of the continuous beam translates, the chord rotations of the three members are zero ($\Psi_{AB} = \Psi_{BC} = \Psi_{CD} = 0$).

Also, supports A and D are fixed, the rotations $\theta_A = \theta_D = 0$. By applying Eq. (9) for member AB, with A as the near end and B as the far end, we obtain the slope-deflection equation

$$M_{AB} = \frac{2EI}{20} \left(0 + {}_{B} - 0 \right) + 50 = 0.1EI_{B} + (18a)$$

Next, by considering B as the near end and A as the far end, we write

$$M_{BA} = \underbrace{2EI}_{200} \left(2_{B} + 0 - 0 \right) - 50 = 0.2EI_{B} - \left(\underbrace{18b}_{39\,28} \right)$$

Slope-Deflection Equations Similarly, by applying Eq. (9) for member BC, we obtain $M_{BC} = \frac{2EI}{20} \begin{pmatrix} 2 \\ B + c \end{pmatrix} + 75 = 0.2EI \\ B + 0.1EI \\ c + 75$ (18c) $M_{CB} = \frac{2EI}{20} \begin{pmatrix} 2 \\ c + B \end{pmatrix} - 75 = 0.2EI \\ c + 0.1EI \\ B - 75$ (18d) and for member CD,

$$M_{CD} = \frac{2EI}{15} \begin{pmatrix} 2 \\ c \end{pmatrix} = 0.267EI_{C}$$
(18e)

$$M_{DC} = \frac{2EI}{15} {\binom{c}{c}} = 0.133EI_{C}$$
(18f)

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Joint Rotations Solving Eqs. (19a) & (19b) simultaneously for El θ_{a} and El θ_{c} , we obtain $EI\theta_{B} = -108.46 k ft^{2}$ $EI\theta_{C} = 183.82 k - ft_{2}$ By substituting the numerical values of E = 29,000 ksi = 29,000(12)_{2} ksf and I = 500 in.4, we determine the rotations of joints B and C to be $\theta_{B} = -0.011 rad$ or 0.011 rad 0 = 0.0018 rad

Joint Rotations

To determine the unknown joint rotations $\theta_{\text{B}} \& \theta_{\text{c}}$, we substitute the slope-deflection equations Eqs. (18) into the joint equilibrium equations Eqs. (17) and solve the resulting systems of equations simultaneously for $\theta_{\text{B}} \& \theta_{\text{c}}$. By substituting Eqs. (18b) and (18c) into Eq. (17a), we obtain

$$(0.2EI\theta_{B} - 50) + (0.2EI\theta_{B} + 0.1EI\theta_{C} + 75) = 0$$

or $0.4EI\theta_{B} + 0.1EI\theta_{C} = -25$ (19*a*)
and by substituting Eqs. (18d) and (18e) into Eq. (17b), we get
 $(0.2EI\theta_{C} + 0.1EI\theta_{B} - 75) + 0.267EI\theta_{C} = 0$
or $0.1EI\theta_{B} + 0.467EI\theta_{C} = 75$ (19*b*)

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Member End Moments The moments at the ends of the three members of the continuous beam can now be determined by substituting the numerical values of $Ei\theta_{B}$ and $Ei\theta_{C}$ into the slope-deflection equations (Eqs. 18). $M_{AB} = 0.1(-108.46)+50 = 39.2 \ k-ft$) $M_{BA} = 0.2(-108.46)-50 = -71.7 \ k-ft$ or $71.7 \ k-ft$) $M_{BC} = 0.2(-108.46)+0.1(183.82)+75 = 71.7 \ k-ft$) $M_{CB} = 0.2(183.82)+0.1(-108.46)-75 = -49.1 \ k-ft$ or $49.1 \ k-ft$) $M_{CD} = 0.267(183.82)=49.1 \ k-ft$) $M_{DC} = 0.133(183.82)=24.4 \ k-ft$)

Member End Moments

To check that the solution of simultaneous equations (Eqs. 19) has been carried out correctly, the numerical values of member end moments should be substituted into the joint equilibrium equations (Eqs. 17). If the solution is correct, then the equilibrium equations should be satisfied.

$M_{BA} + M_{BC} = -71.7 + 71.7 = 0$	Checks
$M_{CB} + M_{CD} = -49.1 + 49.1 = 0$	Checks

The member end moments just computed are shown on the free body diagrams of the members and joints in Figure on next slide.

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2. Fixed-End Moments

By using the fixed-end moment expressions given inside the back cover of the book, we evaluate the fixed-end moments due to the external loads for each member.

$$FEM_{AB} = \frac{wab_2}{L_2} = \frac{18(10)(15)}{25_2} = 64.8 \ k - ft \) \qquad or + 64.8 \ k - ft$$

$$FEM_{BA} = \frac{wa_2b}{L_2} = \frac{18(10)(15)}{25_2} = 43.2 \ k - ft \) \qquad or - 64.8 \ k - ft$$

$$FEM_{BC} = \frac{wL_2}{12} = \frac{2(30)}{12} = 150 \ k - ft \) \qquad or + 150 \ k - ft$$

$$FEM_{CB} = 150 \ k - ft \) \qquad or - 150 \ k - ft$$
Counterclockwise FEM are positive, whereas clockwise FEM are negative.

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3. Chord Rotations

Since no support settlements occur, the chord rotations of both members are zero; that is, $\Psi_{\rm \tiny AB}=\Psi_{\rm \tiny BC}=0.$

4. Slope-Deflection Equations

To relate the member end moments to the unknown joint rotation, θ_{B} , we write the slope deflection equation for the two members of the structure by applying Eq. (9).

$$M_{nf} = \underline{2EI}_{L} \left(2_{n} + f - nf \right)$$
(9)

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since the supports A and C are fixed, the rotations $\theta_A = \theta_C = 0$.

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4. Slope-Deflection Equations Slope-Deflection Equation for Member AB $M_{AB} = 2EI (B) + 64.8 = 0.08EI B + (1)$ $M_{BA} = 2EI (2 B) - 43.2 = 0.16EI B - (2)$ Slope-Deflection Equation for Member BC $M_{BC} = \frac{2EI}{30} (2 B) + 150 = 0.133EI B (3)$ $M_{CB} = 2EI (B) - 150 = 0.0667EI B - 150 (4)$





To determine the unknown joint rotations, $\theta_{\scriptscriptstyle B}$, substitute the slope deflection equations (Eqs. 2 & 3) into the equilibrium equation (Eq. 5).

 $(0.16EI_{B}-43.2)+(0.133EI_{B}+150)=0$

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or

$$0.293EI_{B} = -106.8$$

fromwhich

$$EI_{B} = -364.5 \ k - ft_{2}$$

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7. Member End Moments

The member end moments can now be computed by substituting the numerical value of $EI\theta_{\scriptscriptstyle B}$ back into the slope-deflection equation (Eqs. 1 to 4).

$M_{AB} = 0.08(-364.5) + 64.8 = 35.6 \ k - ft $		
$M_{BA} = 0.16(-364.5) - 43.2 = -101.5 k - ft$	or	101.5 <i>k-ft</i> 🔪
$M_{BC} = 0.133 (-364.5) + 150 = 101.5 k - ft $		
$M_{CB} = 0.0667 (-364.5) - 150 = -174.3k - ft$	or	174.3 <i>k-ft</i>

Positive answer for an end moment indicates that its sense is counterclockwise, whereas a negative answer implies a clockwise sense. As M_{BA} and M_{BC} are equal in magnitude but oppositein sense, the equilibrium equation $M_{BA} + M_{BC} = 0$ is satisfied. MZCET/(CVILV-ABB/CEESDIG.A. I/V) ⁶⁸
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9. Support Reactions

The reactions at the fixed support A and C are equal to the forces and moments at the ends of the members connected to these joints. To determine the reaction at roller support B, consider the equilibrium of the free body of joint B in the vertical direction.

$$B_y = S_{BA} + S_{BC} = 9.84 + 27.57 = 37.41 \ k \uparrow$$
 ANS





10. Equilibrium Check

To check our calculations of member end shears and support reactions, we apply the equations of equilibrium to the free body of the entire structure.









PROBLEM: 4

• Determine the reactions and draw the shear and bending moment diagrams for the continuous beam shown in Figure.



Solution
 From figure we can see that all three joints of the beam are free to rotate. Thus the beam have 3 degrees of freedom, θ_A, θ_B, θ_D.
 The end supports A and D of the beam are simple supports at which no external moment is applied, the moments at the end A of the member AB and at the end D of the member BD must be zero.

MBD

 $M_{AB} = 0$

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M_{DB} = 0

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<u>Solution</u>

• The ends A and D can be considered as hinged ends and the modified slope-deflection equations can be used.

$$M_{rh} = \frac{3EL}{L} \begin{pmatrix} r & - \\ - & - \end{pmatrix} + \begin{pmatrix} rh & -\frac{FEM_{hr}}{2} \end{pmatrix}$$
(15a)
$$M_{hr} = 0$$
(15b)

• The modified SDE do not contain the rotations of the hinged ends, by using these equations the rotations θ_{a} , and θ_{o} of the simple supports can be eliminated, which will then involve only one unknown joint rotation, θ_{B} .





	$(0.3EI_{B}-187.5)+(0.6EI_{B}+30)$	(0) = 0
or		
	$0.9EI_{B} = -112.5$	
fromwhich		
	$EI_{B} = -125 \ kN - m_2$	
7. Member End	Moments	
The membe numerical va 2).	r end moments can now be computed by su alue of $EI\Theta_{\scriptscriptstyle B}$ into the slope-deflection equati	bstituting ons (Eqs.
-7.		
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4. Equilibrium Equations By considering the moment equilibrium of the free body of joint B, we obtain the equilibrium equation

$$M_{BA} \xrightarrow{B} \sum_{M_{BD}} M_{BD}$$

$$M_{BA} + M_{BD} = 0$$
(3)
5. Joint Rotation
Todetermine the unknown joint rotation θ_{B} we substitute the SDE
(Eqs. 1 & 2) into the equilibrium equations Eq. 3 to obtain
$$M_{ECET/(UVLV-ABB/CEES01/SA I/V}$$

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4. Slope-deflection Equations	
$M_{AB} = 0$	ANS
$M_{BA} = \frac{3EI}{10} \left(B_{BA} + 0.0026 \right) - 100 = 0.15EI \pm 0.00039EI - 100$	(1)
$M_{BC} = \frac{2EI}{20} \begin{bmatrix} 2 & B & +_{C} & -3(-0.00365) \end{bmatrix} +$	
$= 0.2EI_{B} + 0.1EI_{C} + 0.0011EI + 66.7$	(2)
$M_{CB} = \frac{2EI}{20} \begin{bmatrix} 2 & c + & B - 3(-0.00365) \end{bmatrix} - 66.7$	
$= 0.1EI_{B} + 0.2EI_{C} + 0.0011EI -$	(3)
$M_{CD} = \frac{3EL}{20} \begin{pmatrix} c & -0.00313 \end{pmatrix} + 100 = 0.15EI_{C} & -0.00047EI \end{pmatrix}$	(4)
$M_{DC} = 0$	ANS
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M _{BA} B) M _{BC}	$M_{BA} + M_{BC} = 0$ $M_{CB} + M_{CD} = 0$	М _{св} с	
6. Joint Rotat	ions			
equilibriu	m equati 0.35 <i>EI</i>	ons (Eqs. 5 & 6), we obtain $_{B} + 0.1EI = -0.0014$	49 <i>EI</i> + 33.3	
	0.1EI	. 0.25 EL 0.000	62 EI 22 2	
	0.1EI	$_{B}+0.35EI$ $_{C}=-0.000$	0 <i>3E1</i> - <i>33.3</i>	
substituti the above	ng EI = (29 e equation	B+ 0.35E1 ⊂ = −0.000 0,000)(7,800)/(12) ₂ k-ft ₂ i ns yields	nto the right sides of	

6. JointRotations	
$0.35EI_{B} + 0.1EI_{C} = -2,307.24$	(7)
• $0.1EI_{B} + 0.35EI_{C} = -1,022.93$	(8)
• By solving Eqs. (7) and (8) simultaneously, we determine the values of $EI\theta_{\scriptscriptstyle B}$ and $EI\theta_{\scriptscriptstyle B}$ to be	
• $EI_{C}^{B} = -6,268.81 k - ft_{2}$ $EI_{C}^{B} = 1,131.57.81 k - ft_{2}$	
7. Member End Moments	
To compute the member end moments, substitute the nume values of $EI\Theta_{a}$ and $EI\Theta_{c}$ back into the slope-deflection equations $1 - 4$ to obtain	erical (Eqs.

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7. Member End Moments $M_{BA} = -427.7 \ k - ft$ or $427 \ k - ft$ ANS $M_{BC} = 427 \ k - ft$ $M_{CB} = 808 \ k - ft$ $M_{CD} = -808 \ k - ft$ or $808 \ k - ft$ ANS ANS ANS 8. Member End Shears and Support Reactions 2 k/ft 41.38 81.79 2 k/ft 41.79 20.4 2 k/ft B C $\begin{array}{c} & & & & & \\ B & _{427.7} & _{427.7} & B & C & C \\ 41.38 & _{81.79} & & 41.79 & C_{\gamma^{=}} 62.19 & 20.4 \\ & & & & \\ B_{\gamma^{=}} 123.17 & & & C_{\gamma^{=}} 62.19 & 20.4 \end{array}$ A D 1.38 60.4 80 MZCET/CIVIL/V-A&B/CE6501/SA I/IV







4.3 Rigid frames without sway

However the frames are symmetrical in geometry and in loading and hence these will not sidesway. In general, frames do not side sway if,

1) They are restrained against side sway.

2) The frame geometry and loading is symmetrical





Step: 3 Slope deflection equation		
$\begin{split} M_{AB} &= M_{FAB} + \frac{2EI}{L} [2\theta_A + \theta_B] = -106.67 + \frac{2E(2I)}{6} \theta_B \\ &= -106.67 + \frac{2EI}{3} \theta_B \end{split}$	(1)	
$\begin{split} M_{BA} &= M_{FBA} + \frac{2EI}{L} [2\theta_{B} + \theta_{A}] = 53.33 + \frac{2E(2I)}{6} 2\theta_{B} = 53.33 + \frac{44}{6} \\ M_{BC} &= M_{FBC} + \frac{2EI}{L} [2\theta_{B} + \theta_{C}] = -26.67 + \frac{3EI}{2} \theta_{B} + \frac{3EI}{4} \theta_{C} \\ M_{CB} &= M_{FCB} + \frac{2EI}{L} [2\theta_{C} + \theta_{B}] = 26.67 + \frac{3EI}{2} \theta_{C} + \frac{3EI}{4} \theta_{B} \\ M_{BD} &= M_{FBD} + \frac{2EI}{L} [2\theta_{B} + \theta_{D}] = 10 + \frac{2EI}{4} 2\theta_{B} + \frac{2EI}{4} \theta_{D} \\ &= 10 + EI\theta_{B} + \frac{EI}{2} \theta_{D} \\ M_{DB} &= M_{FDB} + \frac{2EI}{L} [2\theta_{D} + \theta_{B}] = -10 + \frac{2EI}{4} 2\theta_{D} + \frac{2EI}{4} \theta_{B} \\ &= -10 + EI\theta_{D} + \frac{EI}{2} \theta_{B} \end{split}$	$ \frac{EI}{3}\theta_{B} \qquad \cdots \cdots (2) \\ \qquad \cdots \cdots (3) \\ \qquad \cdots \cdots (4) \\ \qquad \cdots \cdots (5) \\ \qquad \cdots \cdots (6) $	
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Step:3 slope deflection equation

For writing slope-deflection equations two spans must be considered, *BC* and *BD*. Since supports *C* and *D* are fixed $\theta_c = \theta_D = 0$. Also the frame is restrained against sidesway.

$$\begin{split} M_{BD} &= 5 + \frac{2EI}{4} [2\theta_B] = 5 + EI\theta_B \\ M_{DB} &= 5 + \frac{2EI}{4} [\theta_B] = -5 + 0.5EI\theta_B \\ M_{BC} &= EI\theta_B \\ M_{CB} &= 0.5EI\theta_B \end{split}$$

Step:4 Equilibrium equation $\sum M_{B} = 0 \implies M_{BD} + M_{BC} - 10 = 0$ Substituting the value of M_{BD} and M_{BC} $5 + EI\theta_{B} + EI\theta_{B} - 10 = 0$ $\theta_{B} = \frac{2.5}{EI}$

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PROBLEM: 3

• Determine support moments using slope deflection method for the frame shown in figure. Also draw bending moment diagram.

Solution:

(a)Fixed end moments (FEM):

$$M_{f}AB = -\frac{wl^{2}}{12} = -\frac{2.4 \times 4^{2}}{12} = -3.20 \text{ kN}$$

$$M_{f}BA = +\frac{wl^{2}}{12} = +3.20 \text{ kN}$$

$$M_{f}BD = -\frac{wl^{2}}{8} = -\frac{12 \times 3}{8} = -4.5 \text{ kN}$$

$$M_{f}DB = +\frac{wl}{8} = +4.5 \text{ kN}$$

$$M_{f}BC = M_{BC} = -10 \times 1.5 = -15 \text{ kN}$$
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(b) Slope – Deflection equation :

$$\begin{split} & M_{AB} = M_{F}AB + \frac{2EI}{l} \left(2\theta_{A} + \theta_{B} - \frac{3\delta}{l} \right) \\ & = -3.20 + \frac{2EI}{4} \left(0 + \theta_{B} - 0 \right) \qquad [\because \theta_{A} = 0, \delta = 0] \\ & = -3.20 + 0.5EI\theta_{B} \qquad \cdots (1) \end{split}$$

$$\begin{split} & M_{BA} = M_{F}BA + \frac{2EI}{l} \left(2\theta_{B} + \theta_{A} - \frac{3\delta}{l} \right) \\ & = 3.20 + \frac{2EI}{4} (2\theta_{B} + 0 - 0) \\ & = 3.20 + EI\theta_{B} \qquad \cdots (2) \end{split}$$

$$\begin{split} M_{BD} &= M_{F}BD + \frac{2EI}{l} \left(2\theta_{B} + \theta_{D} - \frac{3\delta}{l} \right) \\ &= -4.5 + \frac{2EI}{3} (2\theta_{B} + 0 - 0) \\ &= -4.5 + 1.333EI\theta_{B} \quad \cdots (3) \end{split}$$
$$\begin{split} M_{DB} &= M_{F}DB + \frac{2EI}{l} \left(2\theta_{D} + \theta_{B} - \frac{3\delta}{l} \right) \\ &= 4.5 + \frac{2EI}{3} (0 + \theta_{B} - 0) \\ &= 4.5 + 0.67EI\theta_{B} \quad \cdots (4) \end{split}$$



















5. Equilibrium E	quations	
·	$M_{CA} + M_{CD} = 0$	(7)
	$M_{DB} + M_{DC} = 0$	(8)
To establish the the equilibrium equation obtain	hird equilibrium equation n $\Sigma F_x = 0$ to the free body 40 kN	, we apply the force of the entire frame, to
$S_{AC} + S_{BD} = 0$	c↓	D
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4. Slope-Deflection Equations	
$M_{AC} = \frac{2EI}{7} \left(\begin{array}{c} c & -3\left(-\Delta\right) \\ c & -3\left(-\Delta\right) \end{array} \right) = 0.286EI c +0.122EI\Delta$	(1)
$M_{CA} = \frac{2EI(1-1)}{7} \left[2 - c - 3\left(\frac{\Delta}{7}\right) \right] = 0.571EI - c + 0.122EI\Delta$	(2)
$M_{BD} = \frac{2EI}{5} \left(\begin{array}{c} -3\left(-\frac{\Delta}{5}\right) \right) = 0.4EI \\ 0 - 3\left(-\frac{\Delta}{5}\right) = 0.4EI \right) = 0.24EI\Delta$	(3)
$M_{DB} = \frac{2EI}{5} \left(2 \qquad D - 3 \left(-\frac{\Delta}{5} \right) \right) = 0.8EI D + 0.24EI\Delta$	(4)
$M_{CD} = \underline{2EI} \begin{pmatrix} 2 & c & +_D \end{pmatrix} + 39.2 = 0.571 E \xi + 0.286 \xi I +$	(5)
$M_{DC} = \frac{2EL}{7} \begin{pmatrix} c + 2_{D} \end{pmatrix} - 29.4 = 0.286EI_{C} + 0.571E_{D} - 0.286EI_{C} + 0.571E_{D} \end{pmatrix} - 0.286EI_{C} + 0.571E_{D} - 0.286EI_{C} + 0.571E_{D} + 0.571E_{D} - 0.286EI_{C} + 0.571E_{D} - 0.57$	(6)
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5. Equilibrium Equations

To express the column end shears in terms of column end moments, we draw the free body diagram of the two columns and sum the moments about the top of each column:





8. Equilibrium check	
By substituting the numerical values of $EI\Theta_c$, $EI\Theta_o$, and $EI\Delta$ into the slope-deflection equations (Eqs. 1 through 6), we obtain	he
$M_{C4} + M_{CD} = -26 + 26 = 0$	Checks
$M_{DB} + M_{DC} = 21.3 - 21.3 = 0$	Checks
$5(M_{AC} + M_{CA}) + 7(M_{BD} + M_{DB}) = 5(-14.6 - 26) + 7(7.7 + 21.3) = 0$	Checks
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6. Joints Displacements















4. Slope-Deflection Equations	
$M_{AC} = \frac{2EI}{20} (_{C} -3(-0.0625\Delta)) = 0.1EI_{C} +$	(1)
$M_{CA} = \frac{2EI}{20} \left(2 c - 3(-0.0625\Delta) \right) = 0.2EI c + 0.0188EI\Delta$	(2)
$M_{BD} = \frac{2EI}{16} \begin{pmatrix} D & -3(-0.0625\Delta) \end{pmatrix} = 0.125EI_{D} + 0.125EI_{D} \end{pmatrix}$	(3)
$M_{DB} = \frac{2EI}{16} \begin{pmatrix} 2 & -3(-0.0625\Delta) \end{pmatrix} = 0.25EI_{D} + $	(4)
$M_{CD} = \frac{2EI}{20} \begin{pmatrix} 2 & _{C} & +_{D} & (0.0375\Delta) \end{pmatrix} = 0.2EI & _{C} + 0.1EI & _{D} - 0.0113EI\Delta$	(5)
$M_{DC} = \frac{2EI}{20} \left(2_{D} + C_{C} - 3(0.0375\Delta) \right) = 0.2EI_{D} + 0.1E_{C}I - 0.1E_{C}I_{C} - 0.1E_{C}I_{C} - 0.1E_{C}I_{C}I_{C} - 0.1E_{C}I_{C}I_{C}I_{C} - 0.1E_{C}I_{C}I_{C}I_{C}I_{C}I_{C}I_{C}I_{C}I$	(6)
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5. Equilibrium Equations

By considering the moment equilibrium of joints C and D, we obtain the equilibrium equations

$$M_{CA} + M_{CD} = 0 \tag{7}$$

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$$M_{DB} + M_{DC} = 0 \tag{8}$$

The third equilibrium equation is established by summing the moments of all the forces and couples acting on the free body of the entire frame about point *O*, which is located at the intersection of the longitudinal axes of the two columns as shown.

+
$$(\Sigma M_0 = 0 \qquad M_{AC} - S_{AC} (53.33) + M_{BD} - S_{BD} (42.67) + 30 (26.67) = 0$$

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by substituting these expressions into the third equilibrium equation, we obtain

$$1.67M_{AC} + 2.67M_{CA} + 1.67M_{BD} + 2.67M_{DB} = 800$$
(9)

6. Joint Displacements

Substitution of the slope-deflection equations Eqs. 1 to 6 into the equilibrium equations Eqs. 7 to 9 yields

$$0.4EI_{c} + 0.1EI_{D} + 0.0075EI\Delta$$
(10)

 $\langle \rangle$

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$$0.1EI_{c} + 0.45EI_{b} + 0.0121EI\Delta = 0$$
(11)
0.71EI_{c} + 0.877EI_{c} + 0.182EIA_{c} = 800 (11)

$$EI\theta_{c} = -66.648 \,\mathrm{k} \cdot \mathrm{ft}^{2}$$
(12)

$$EI\theta_{D} = -125.912 \text{ k} - \text{ft}^{2}$$

$$EI\Delta = 5,233.6 \,\mathrm{k} - \mathrm{ft}^3$$

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7. Member End Moments

By substituting the numerical values of $EI\theta_c$, $EI\theta_D$, and $EI\Delta$ into the slope-deflection equations (Eqs. 1 through 6), we obtain

$M_{AC} = 91.7 \text{ k} - \text{ft}$			ANS	
$M_{CA} = 85.1 \text{ k} - \text{ft}$			ANS	
$M_{BD} = 106.7 \text{ k} - \text{ft}$			ANS	
$M_{DB} = 91 \text{ k} - \text{ft}$			ANS	
$M_{CD} = -85.1 \mathrm{k} - \mathrm{ft}$	or	85.1k -ft 🐊	ANS	
$M_{DC} = -91 \text{ k} - \text{ft}$	or	91k-ft)	ANS	
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$$\mathcal{M}_{BC} = \mathcal{M}_{f}BC + \frac{2BI}{l} \left(2\theta_{B} + \theta_{C} - \frac{3\delta}{l} \right)$$

$$= -96 + \frac{2B(2I)}{10} (2\theta_{B} + \theta_{C} - 0)$$

$$= -96 + 0.8BI\theta_{B} + 0.4BI\theta_{C} \dots (3)$$

$$\mathcal{M}_{CB} = \mathcal{M}_{f}CB + \frac{2BI}{l} \left(2\theta_{C} + \theta_{B} - \frac{3\delta}{l} \right)$$

$$= 144 + 0.4BI\theta_{B} + 0.8BI\theta_{C} \dots (4)$$
(C) Equilibrium equations:

$$\mathcal{M}_{Bi} + \mathcal{M}_{BC} = 0 \dots (A)$$

$$\mathcal{M}_{Cii} = 0 \dots (B)$$

$$\mathcal{M}_{Bi} + \mathcal{M}_{BC} = 0$$
(160 + 0.5BI θ_{a}) + (-96 + 0.8BI θ_{a} + 0.4EI θ_{C}) = 0
 $\therefore 1.3BI\theta_{a} + 0.4BI\theta_{c} = -64 \dots (A)$

$$\mathcal{M}_{Cii} = 0,$$
 $\therefore 0.4EI\theta_{c} + 0.8BI\theta_{c} + -144 \dots (B)$
Solving equation (A) and (B) by calculator .
Mode \Rightarrow equations $\Rightarrow 2unknowns$
 $\therefore \theta_{B} = \frac{7.272}{BI} \dots clockwise$
 $2ucrychydynaBycessol2BI/VV \dots anticlockw ise$
 $2ucrychydynaBycessol2BI/VV = 142$

(d) Final Moments : $M_{AB} = -160 + 0.25 EI \theta_{B}$ $= -160 + 0.25 EI \left(\frac{7.272}{EI}\right)$ = - 158 .18 kN .m $M_{BA} = 160 + 0.5 EI \left(\frac{7.272}{EI}\right)$ = 163 .64 kN .m $M_{BC} = -96 + 0.8 EI \theta_{B} + 0.4 EI \theta_{B}$ $= -96 + 0.8 EI \left(\frac{7.272}{EI}\right) + 0.4 EI \left(-\frac{183.63}{EI}\right)$ = - 96 + 5.82 - 73.45 = - 163 .64 kN .m $M_{CR} = 144 + 0.4 EI \theta_{R} + 0.8 EI \theta_{R}$ $= 144 + 0.4 EI \left(\frac{7.272}{EI}\right) + 0.8 EI \left(-\frac{183.63}{EI}\right)$ = 144 + 2.91 - 146 .90 = 0 143 MZCET/CIVIL/V-A&B/CE6501/SA I/IV



4.7 Support displacements PROBLEM:1

Determine the reactions and draw the shear and moment curves for the beam. The support at A has been accidentally constructed with a slope that makes an angle of 0.009 rad with the vertical y-axis through support A, and B has been constructed 1.2 in below its intended position. Given: EI is constant, $1= 360 \text{ in}_4$, and $E = 29,000 \text{ kips/in}_2$.

Solution:



























